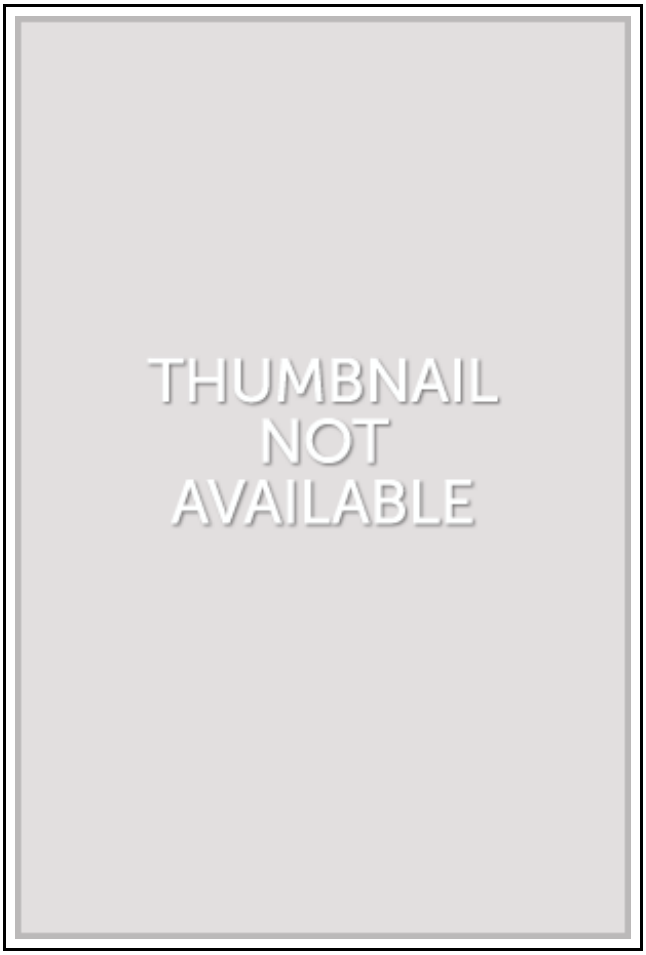
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paperback. Book Condition: New. Ship out in 2 business day, And Fast shipping, Free Tracking number will be provided after the shipment.Pages Number: 311 Publisher: Wuhan University Press Pub. Date :2002-1-1. Book is based on the movement of electric drive control systems for the theoretical background and technical basis. Book for the DC drive system first introduced DC motor speed closed-loop system. dual closed-loop system. reversible system and jump-speed pulse-width system. which features automatic control theory combined with the DC transmission technology. Second is the frequency control of induction motor center to introduce the AC variable speed system. the key theories and techniques. such as inverter. vector control. sinusoidal pulse width modulation and direct torque control. but also describes the synchronous motor vector control. On the basis of the previous two. third to position servo system as the main object. describes some of the special principles and applications of motor execution. as well as the location and trajectory control some of the topics. The article also includes hydraulic. pneumatic and robot motion control system of a profile. Book learning needs electrical and electronic circuits. power electronics. motor and drag. computer theory and automatic control theory based on information as a specialty electrical materials and undergraduate teaching reference books are also available for graduate students and engineering technical officers. Contents: 0 Introduction 1 first speed DC drive system controlled by closed loop speed control system 1.1 speed closed-loop speed control system of the composition and static properties of 1.2 and no static error integral speed control system. the ratio of negative voltage feedback control law 1.3 Current Compensation control of the speed control system Summary Problem 2 multi-loop control of DC Motor Control System 2.1 pairs of closed-loop system structure 2.2 speed. double-loop speed control system and its current characteristics 2.3...

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